## IN THE CLAIMS:

## **Listing of Claims:**

- 1 Claim 1. (currently amended) An emitter locator system, comprising:
- a mobile DF set, said set comprising a receiver for receiving incident signal
- 3 transmissions;
- a line of bearing (LOB) generating system in operative communication with said
- 5 receiver and configured to generate lines of bearing responsive to said received signal
- 6 transmissions;
- an LOB error generating system in operative communication with said line of
- 8 bearing generating system and configured to generate error <u>boundsfactors</u> related to said
- 9 lines of bearing, said line of bearing generating system and said LOB error generating
- 10 system executed by a computing device, said computing device operatively generating a
- 11 cross-over point, said cross-over point defined as the intersection of a pair of sequential
- 12 real-time lines of bearing from said mobile DF set, each said line of bearing
- 13 corresponding to a wireless transmission from said transmitter received by said mobile
- 14 DF set and said computing device then estimates a future position of said transmitter in
- 15 reference to said cross-over point;
- an probability overlay generating system in operative communication with said
- 17 LOB error generating system and configured to generate an overlay probability map
- 18 responsive to said error boundsfactors; and
- display means for visually displaying said lines of bearing, said error
- 20 <u>boundsfactors</u> and said overlay map.
- 1 Claim 2. (currently amended) The system of Claim 1, wherein:
- 2 said incident signal transmissions are further defined by strength and clarity
- 3 factors;

- said line of bearing generating system further generates quality numbers for each
- 5 said line of bearing responsive to said strength and clarity factors; and
- said LOB error generating system generates said error boundsfactors responsive
- 7 to said quality numbers.

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- 1 Claim 3. (currently amended) The system of Claim 2, further comprising a second DF
- set in communication with said mobile DF set, said second set comprising a receiver for
- 3 receiving incidental signal transmissions, the system further comprising:
- 4 said line of bearing generating system:
- 5 said LOB error generating system;
- 6 said probability overlay generating system; and
- 5 said display means for further visually displaying said lines of bearing, said error
- 8 boundsfactors and said overlay map, said lines of bearing generated by said mobile DF
- 9 set and said second DF set.
- 1 Claim 4. (original) The system of Claim 3, wherein said display means of said mobile
- 2 DF set further displays said lines of bearing generated by said second DF set.
- Claim 5. (original) The system of Claim 2, wherein said mobile DF set further
- 2 comprises a position estimating system for determining the spacial location of said
- 3 transmitter responsive to said lines of bearing and said LOB errors.
- Claim 6. (original) The system of Claim 5, wherein said display means further displays
- 2 said spacial location of said transmitter.
- Claim 7. (original) The system of Claim 6, wherein said probability overlay generating
- 2 system is further responsive to said spacial location of said transmitter.
- 1 Claim 8. (original) The system of Claim 7, wherein said probability overlays comprise
- 2 a two-dimensional composite of concentric shapes.

- 1 Claim 9. (currently amended) The system of Claim 8, wherein said concentric shapes
- 2 comprise an inner shape concentric to an outer shape, said inner shape configuration
- 3 representative of said error boundsfactors having relatively small values and said outer
- 4 shape configuration representative of said error boundsfactors having relatively large
- 5 values.
- 1 Claim 10. (currently amended) A direction-finding method comprising the steps of:
- 2 establishing a cross-over position point;
- 3 relocating a receiver to a new receiver spacial location;
- said receiver at said new receiver position receiving a transmission from a
- 5 transmitter at a transmitter position;
- determining a real-time line of bearing from said receiver to said transmitter;
- 7 generating a connecting vector from said real-time line of bearing to said cross-
- 8 over position point; and
- 9 identifying a real-time position of said transmitter along said connecting vector;
- displaying said real-time position on a user display panel; and
- generating and displaying an probability overlay map responsive to said real-time
- 12 position and asaid quality factor on said user display panel.
- 1 Claim 11. (original) The method of Claim 10, wherein said identifying step further
- 2 comprises assigning a probability factor to said real-time position of said transmitter
- 3 responsive to said quality factor and said probability overlay map generating and
- 4 displaying is responsive to said probability factor.
- Claim 12. (original) The method of Claim 11, further comprising a repeating step to
- 2 repeat said relocating, receiving, determining, generating, identifying, displaying and
- 3 generating steps until said probability factor exceeds a predetermined threshold value.

- 1 Claim 13. (original) The method of Claim 11, further comprising a repeating step to
- 2 repeat said relocating, receiving, determining, generating, identifying, displaying and
- 3 generating steps until said probability factor meets a user-defined threshold value.
- 1 Claim 14. (original) The method of Claim 11, further comprising a repeating step to
- 2 repeat said relocating, receiving, determining, generating, identifying, displaying and
- 3 generating steps until a user terminates said direction finding method.